Autonics

Side Mount Type Incremental Rotary Encoders

ENA Series

PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.
The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Features

- Die-cast external housing provides excellent immunity to impact
- Designed to mount directly onto frames
- Various resolutions: 1 to 5000 pulses per revolution
- Various control output options
- Power supply: 5 VDC⎓ ± 5%, 12 - 24 VDC⎓ ± 5%

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ⚠ symbol indicates caution due to special circumstances in which hazards may occur.

⚠ Warning Failure to follow instructions may result in serious injury or death.

01. **Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)**
    Failure to follow this instruction may result in personal injury, economic loss or fire.
02. **Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.**
    Failure to follow this instruction may result in explosion or fire.
03. **Install on a device panel to use.**
    Failure to follow this instruction may result in fire.
04. **Do not connect, repair, or inspect the unit while connected to a power source.**
    Failure to follow this instruction may result in fire.
05. **Check 'Connections' before wiring.**
    Failure to follow this instruction may result in fire.
06. **Do not disassemble or modify the unit.**
    Failure to follow this instruction may result in fire.

⚠ Caution Failure to follow instructions may result in injury or product damage.

01. **Use the unit within the rated specifications.**
    Failure to follow this instruction may result in fire or product damage.
02. **Do not short the load.**
    Failure to follow this instruction may result in fire.
03. **Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.**
    Failure to follow this instruction may result in product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'.
  Otherwise, It may cause unexpected accidents.
- 5 VDC⎓, 12 - 24 VDC⎓ power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.
- When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments.
  - Indoors (in the environment condition rated in 'Specifications')
  - Altitude max. 2,000 m
  - Pollution degree 2
  - Installation category II

CE EAC

Cautions during Installation

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft.
  Failure to follow this instruction may result in product damage.
- When fixing the product or coupling with a wrench, tighten under 0.15 N m.
- If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be shorten.
- Do not apply tensile strength over 30 N to the cable.

Ordering Information

This is only for reference, the actual prodcut does not support all combinations.
For selecting the specified model, follow the Autonics website.

ENA - ❶ - ❷ - ❸ - ❹

❶ Resolution
Number: Refer to resolution in 'Specifications'

❷ Output phase
2: A, B
3: A, B, Z

❸ Control output
T: Totem pole output
N: NPN open collector output
V: Voltage output

❹ Power supply
5: 5 VDC⎓ ±5%
24: 12 - 24 VDC⎓ ±5%

Product Components

- Product (+ connector cable)
- Instruction manual
- Bolt × 4
- Coupling × 1

Connections

- Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately.

■ A, B phase output model

Pin	Color	Function	Pin	Color	Function
1	Black	OUT A	3	Brown	+V
2	White	OUT B	4	Blue	GND

• SCN-16-4P pin layout

■ A, B, Z phase output model

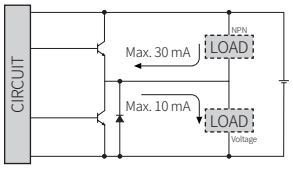
Pin	Color	Function	Pin	Color	Function
1	Black	OUT A	4	Brown	+V
2	White	OUT B	5	Blue	GND
3	Orange	OUT Z	—		

• SCN-16-5P pin layout

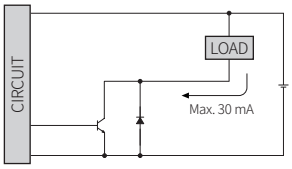
Inner Circuit

- Output circuits are identical for all output phase.

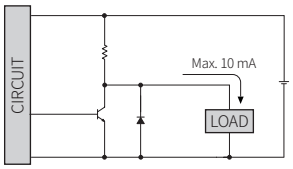
■ Totem pole output



■ NPN open collector output

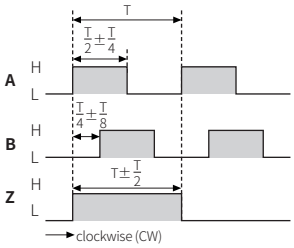


■ Voltage output



Output Waveform

- The rotation direction is based on facing the shaft, and it is clockwise (CW) when rotating to the right.
- Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T = 1 cycle of A)



Specifications

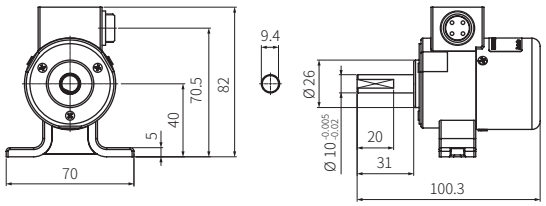
Model	ENA-□-□-T-□	ENA-□-□-N-□	ENA-□-□-V-□
Resolution	1 / 2 / 5 PPR 01) 10 to 5,000 PPR model		
Control output	Totem pole output	NPN open collector output	Voltage output
Output phase	A, B / A, B, Z output model	A, B / A, B, Z output model	A, B / A, B, Z output model
Inflow current	≤ 30 mA	≤ 30 mA	-
Residual voltage	≤ 0.4 VDC⎓	≤ 0.4 VDC⎓	≤ 0.4 VDC⎓
Outflow current	≤ 10 mA	-	≤ 10 mA
Output voltage (5 VDC⎓)	≥ (power supply -2.0) VDC⎓	-	-
Output voltage (12 - 24 VDC⎓)	≥ (power supply -3.0) VDC⎓	-	-
Response speed 02)	≤ 1 μs		
Max. response freq.	300 kHz		
Max. allowable revolution 03)	5,000 rpm		
Starting torque	≤ 0.007 N m		
Inertia moment	≤ 80 g·cm^2 (8 × 10^{-6} kg·m^2)		
Allowable shaft load	Radial: ≤ 10 kgf, Thrust: ≤ 2.5 kgf		
Unit weight	≈ 345 g		
Approval	CE EAC		

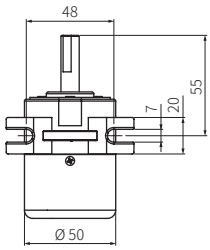
01) Depending on the control ouput, only A, B are output.
02) Based on cable length: 2 m, I sink: 20 mA
03) Select resolution to satisfy Max. allowable revolution ≥ Max. response revolution
[max. response revolution (rpm) = $\frac{\text{max. response frequency}}{\text{resolution}} \times 60$ sec]

Power supply	5 VDC⎓ ± 5% (ripple P-P: ≤ 5%) / 12 - 24 VDC⎓ ± 5% (ripple P-P: ≤ 5%) model
Current consumption	≤ 80 mA (no load)
Insulation resistance	Between all terminals and case: ≥ 100 MΩ (500 VDC⎓ megger)
Dielectric strength	Between all terminals and case: 750 VAC∼ 50 / 60 Hz for 1 minute
Vibration	1 mm double amplitude at frequency 10 to 55 Hz (for 1 minute) in each X, Y, Z direction for 2 hours
Shock	≲ 75 G
Ambient temp.	-10 to 70 °C, storage: -25 to 85 °C (no freezing or condensation)
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)
Protection rating	IP50 (IEC standard)
Connection	Radial connector type
Cable spec.	Ø 5 mm, 2 m, shield cable A, B phase output model: 4-wire / A, B, Z phase output model: 5-wire
Wire spec.	AWG24 (0.08 mm, 40-core), insulator diameter: Ø 1 mm
Connector spec.	A, B phase output model: SCN-16-4P socket type A, B, Z phase output model: SCN-16-5P socket type

Dimensions

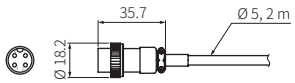
- Unit: mm, For the detailed drawings, follow the Autonics website.



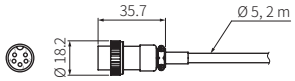


■ Connector cable

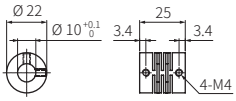
- 4-pin connector cable



- 5-pin connector cable



■ Coupling



- Parallel misalignment: ≤ 0.25 mm
- Angular misalignment: ≤ 5°
- End-play: ≤ 0.5 mm